

Perceptive Kuramoto Oscillators - PeKO

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Synchrony is a natural phenomenon



Outline

Recap: Oscillator Network

- ▶ Previous talk: Perceptual Grouping with Oscillators

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- ▶ Oscillator described by phase θ and frequency ω

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- ▶ Oscillator described by phase θ and frequency ω
- ▶ Phase update:

$$\dot{\theta}_m = \omega_m + \frac{K}{N} \sum_{n=1}^N \mathbf{F}_{mn} \sin(\theta_n - \theta_m)$$

- ▶ Frequency update:

$$\omega_m = \omega_0 \cdot \operatorname{argmax}_{\alpha} \left(\sum_{n \in \mathcal{N}(\alpha)} \mathbf{F}_{mn} \cdot \frac{1}{2} (\cos(\theta_n - \theta_m) + 1) \right)$$

Recap: Evaluation

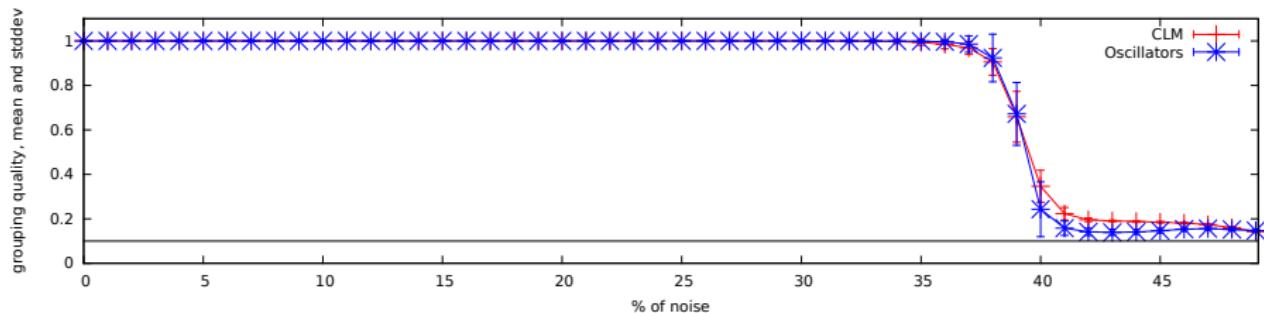
- ▶ Comparison to the CLM, similar settings for both
- ▶ IA matrix with 1000 features in ten groups
- ▶ 100 layers, 100 discrete frequencies
- ▶ All with different amounts of noise in the IA matrices
- ▶ 500 trials for each condition

Recap: Evaluation Results

- ▶ Previous talk: Evaluation results

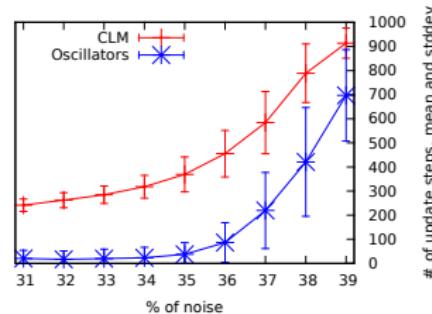
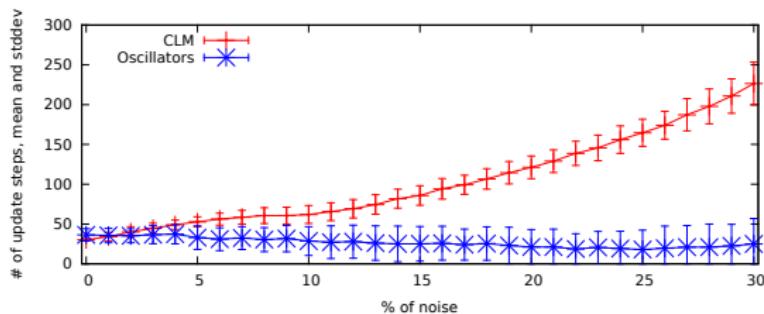
Recap: Evaluation Results

- ▶ Previous talk: Evaluation results
- ▶ Evaluation revealed:
 - ▶ Quality comparable to the CLM



Recap: Evaluation Results

- ▶ Previous talk: Evaluation results
- ▶ Evaluation revealed:
 - ▶ Quality comparable to the CLM
 - ▶ Computational complexity reduced
 - ▶ Grouping speed increased

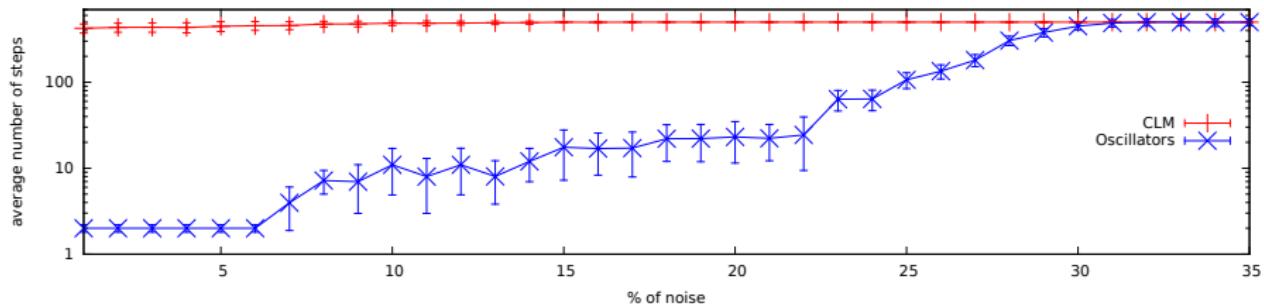


New: Robustness to Perturbations

- ▶ Both models converge for 500 steps
- ▶ Split target groups ($10 \rightarrow 20$)
- ▶ Measure #steps needed for new grouping result

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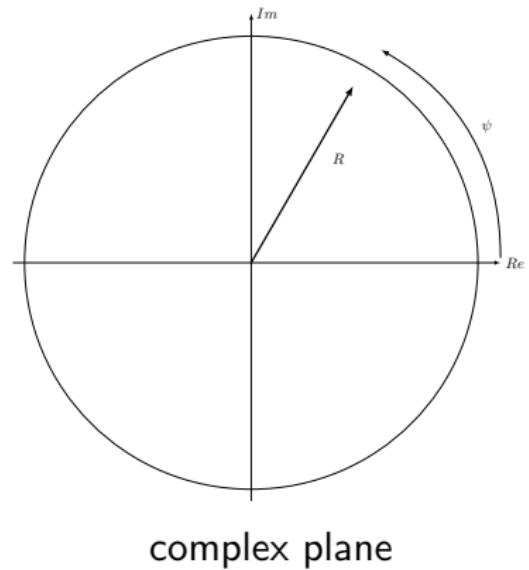
Stability

- ▶ PeKO achieves good grouping results.
- ▶ How to assess the grouping quality?



Kuramoto Order Parameter

- ▶ Complex parameter, r and ψ
- ▶ $re^{i\psi} = \frac{1}{N} \sum_{n=1}^N e^{i\theta_n}$
- ▶ r is phase coherence $\in [0, 1]$
- ▶ ψ is average phase

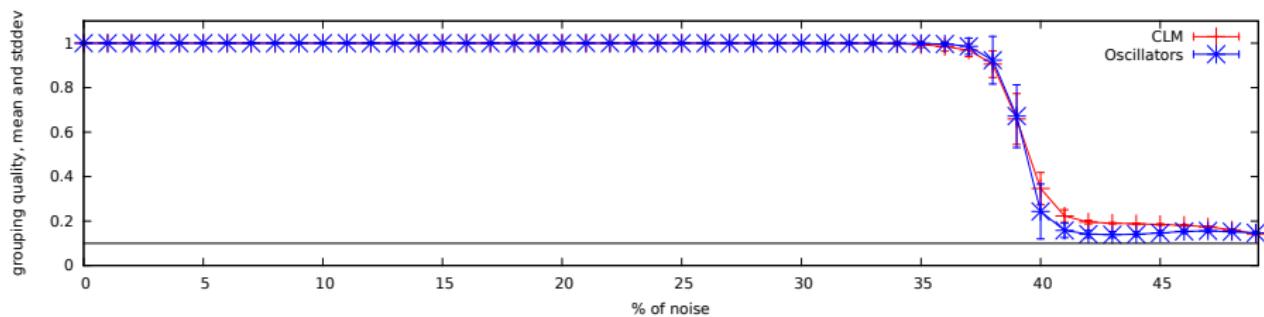


Order Parameter

- ▶ Needs to be adapted for discrete frequencies:

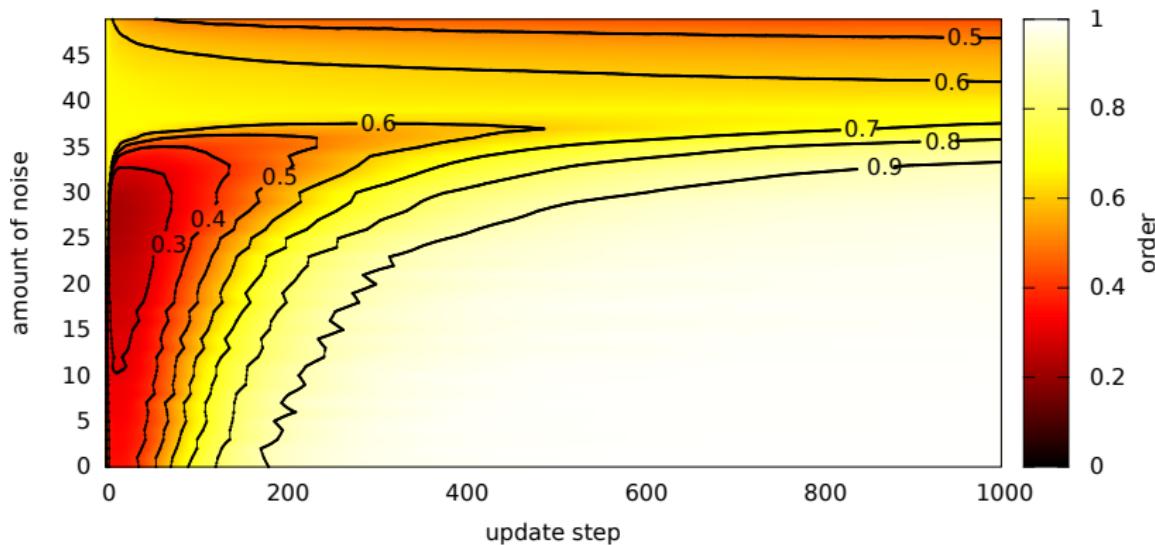
$$r_\alpha e^{i\psi_\alpha} = \frac{1}{N_\alpha} \sum_{n=1}^{N_\alpha} e^{i\theta_n} \quad \text{if } N_\alpha \neq 0$$

Order Behavior



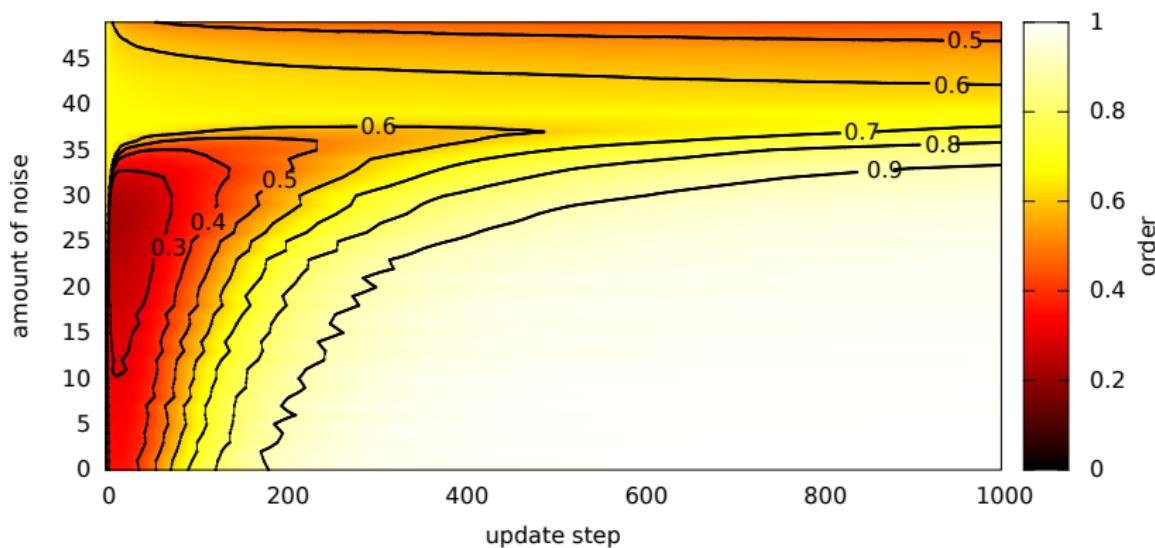
- ▶ Recap: Grouping quality with respect to noise

Order Behavior



- ▶ Order parameter \bar{r} wrt. noise and time

Order Behavior



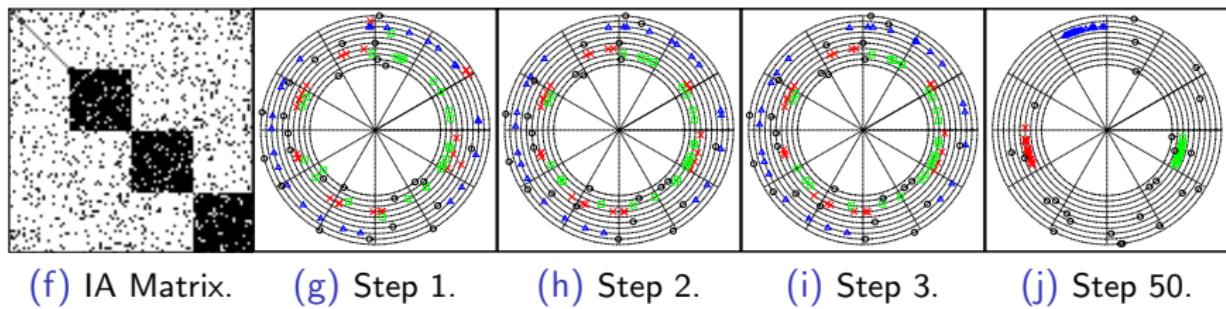
- ▶ Order parameter can be used to assess grouping quality

Dealing with spurious features

- ▶ Everyone knows: Not every feature is relevant
- ▶ We have to deal with them

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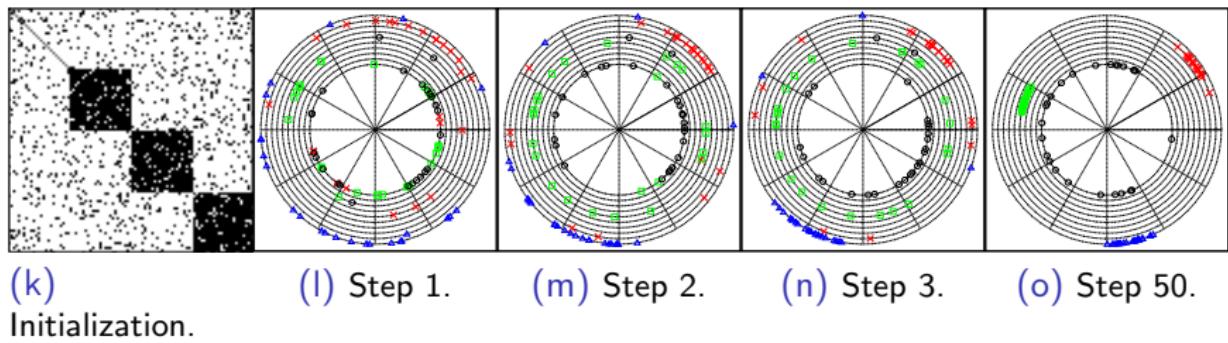
Dealing with spurious features

- ▶ Background Layer: Nice idea “borrowed” from the CLM
- ▶ Introduced as special frequency
- ▶ Possesses “chaotic” coupling:

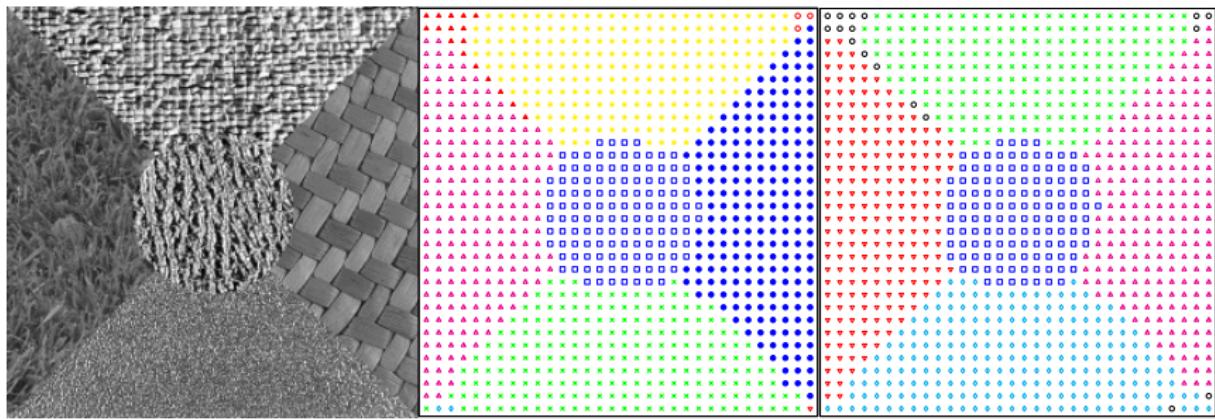
$$\dot{\theta}_m = \omega_m + Kr \sin(\psi - \theta_m).$$

Dealing with spurious features

- ▶ Same example as before
- ▶ Spurious features are collected by the background frequency



Real World Example: Texture Grouping



(p) Input image.

(q) Without background.

(r) With background.

Improved Learning of Lateral Interactions

- ▶ Idea from S. Weng
- ▶ Represent feature compatibility by distance functions
- ▶ Create prototypes with VQ
- ▶ Labeled examples are used to decide if $+$ / $-$ interaction

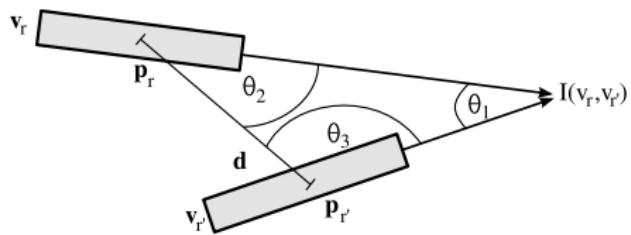
Improved Learning of Lateral Interactions

- ▶ Original approach used Activity Equilibrium VQ
- ▶ Replaced by ITVQ
 - ▶ Better distribution of prototypes
- ▶ Evaluated in contour grouping task

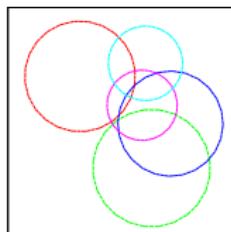
Improved Learning of Lateral Interactions

- ▶ Evaluated with three kinds of shapes
- ▶ 200 trials for each shape
- ▶ Four conditions
 - ▶ CLM with AEV
 - ▶ PeKO with AEV
 - ▶ CLM with ITVQ
 - ▶ PeKO with ITVQ

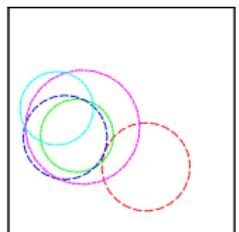
Feature and Data Example



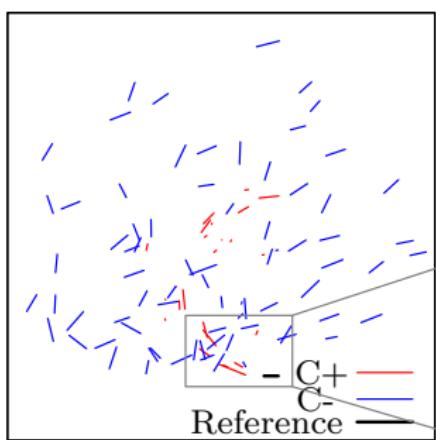
(s) Oriented edge features.



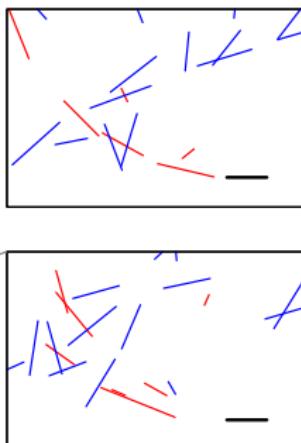
(t) “Easy” problem. (u) “Hard” problem.



Example of generated Prototypes

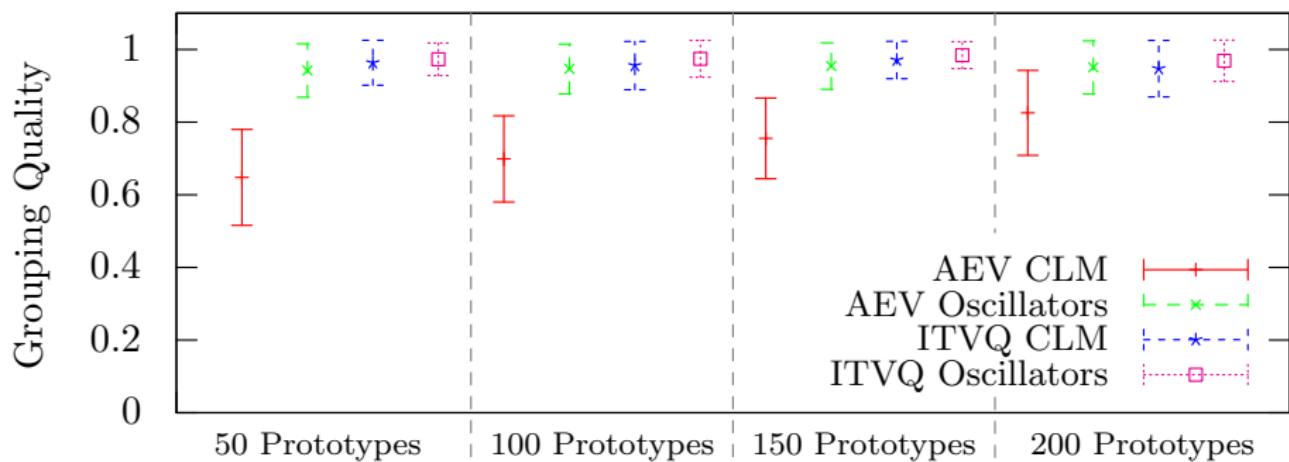


ITVQ Prototypes



AEV Prototypes

Improved Learning of Lateral Interactions - Results



Conclusion

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Conclusion

- ▶ Oscillators are robust to perturbations
- ▶ Order allows assessment of grouping quality
- ▶ “Chaotic” frequency handles spurious features
- ▶ Learning of lateral interactions is improved

Thank You!

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Any Questions?

ITVQ Update Rule

- ▶ Minimize Cauchy-Schwartz Divergence
- ▶ x_0 is input, x prototypes
- ▶ Fixed point update rule:

$$x_i^{t+1} = \frac{\sum_{j=1}^{N_0} G_\sigma(x_i^t - x_{0j}) x_{0j}}{\sum_{j=1}^{N_0} G_\sigma(x_i^t - x_{0j})} - c \frac{\sum_{j=1}^N G_\sigma(x_i^t - x_j^t) x_j^t}{\sum_{j=1}^{N_0} G_\sigma(x_i^t - x_{0j})} + c \frac{\sum_{j=1}^N G_\sigma(x_i^t - x_j^t)}{\sum_{j=1}^{N_0} G_\sigma(x_i^t - x_{0j})} x_i^t; \quad c = \frac{N_0}{N} \frac{V(X, X_0)}{V(X)}$$

Learning of Lateral Interactions

